

# One decomposition of hyperbolic unitary matrices

Vedran Šego

Faculty of Science, Department of Mathematics, University of Zagreb

7<sup>th</sup> Conference on Applied Mathematics and Scientific Computing  
Trogir, Croatia, 13.6.2011.

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Theory

Application

Conclusion



# Outline

- 1 Introduction
- 2 Theory
- 3 Application
- 4 Conclusion



*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

Conclusion

# Introduction

- 1 Introduction
  - Basic terms
  - We shall need
  - Motivation
- 2 Theory
- 3 Application
- 4 Conclusion



*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Basic terms

We shall need

Motivation

Theory

Application

Conclusion



## Notation

- $\mathbb{F} = \mathbb{C}$  or  $\mathbb{F} = \mathbb{R}$ ,
- $x, y, \dots \in \mathbb{F}^n$ ,  $A, B, \dots \in \mathbb{F}^{m \times n}$ ,
- Euclidean scalar product:  $\langle x, y \rangle := y^* x$ ,
- Hyperbolic scalar product induced by  $J = \text{diag}(\pm 1)$ :

$$[x, y]_J := y^* J x.$$

When  $J$  is known from context:  $[x, y]$ ,

- $\lambda(A)$  – set of eigenvalues of  $A$ ,
- $\arg(z)$  argument (angle) of  $z \in \mathbb{C}$ ,
- “norm” of  $x$ :  $[x, x]$  – can be negative!

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

**Basic terms**

We shall need

Motivation

Theory

Application

Conclusion



## Hermitian matrices

- Euclidean adjoint (conjugate transpose) of  $A$ :

$$\langle Ax, y \rangle = \langle x, A^* y \rangle,$$

Hermitian matrix  $H$ :

$$H^* = H.$$

- Hyperbolic adjoint of  $A$ :

$$[Ax, y] = [x, A^{[*]}y], \text{ i.e. } A^{[*]} = JA^*J,$$

$J$ -Hermitian matrix  $H$ :

$$H^{[*]} = H, \text{ i.e. } JH = HJ.$$

Matrix  $H$  is  $J$ -Hermitian if and only if  $JH$  is Hermitian.

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

**Basic terms**

We shall need

Motivation

Theory

Application

Conclusion



# Unitary matrices

- Euclidean unitary matrix  $U$ :

$$\langle Ux, Uy \rangle = \langle x, y \rangle, \text{ i.e. } U^*U = I, UU^* = I,$$

- $J$ -unitary matrix:

$$[Ux, Uy] = [x, y],$$

i.e.

$$U^*JU = J, \quad U^{[*]}U = I, \quad UJU^* = J, \quad UU^{[*]} = I,$$

**Note:** Last two not true for more general  $J$ .

- Hyperexchange – “unitary-like” – matrix:

$$UP \text{ is } J\text{-unitary for some permutation } P.$$

Importance: permutations are generally **not**  $J$ -unitary!

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

**Basic terms**

We shall need

Motivation

Theory

Application

Conclusion



## (Principal) square root

Defined for  $A \in \mathbb{F}^{n \times n}$ ,  $\lambda(A) \cap \mathbb{R}_0^- = \emptyset$ .

$\sqrt{A} := X$ , such that:

- ①  $X^2 = A$ ,
- ②  $\lambda(X) \subset \{z \in \mathbb{C} : -\frac{\pi}{2} < \arg(z) < \frac{\pi}{2}\}$ .

Such  $X$  is unique.

### Properties

$$\sqrt{A} = \sum_{k=0}^{\infty} \binom{p}{k} (A - I)^k$$

$$\Rightarrow \sqrt{\cdot} \text{ is analytic}$$

$$\Rightarrow \sqrt{ABA} = A\sqrt{BA}.$$

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Basic terms

**We shall need**

Motivation

Theory

Application

Conclusion



## (Principal) square root

Defined for  $A \in \mathbb{F}^{n \times n}$ ,  $\lambda(A) \cap \mathbb{R}_0^- = \emptyset$ .

$\sqrt{A} := X$ , such that:

- 1  $X^2 = A$ ,
- 2  $\lambda(X) \subset \{z \in \mathbb{C} : -\frac{\pi}{2} < \arg(z) < \frac{\pi}{2}\}$ .

Such  $X$  is unique.

### Properties

$$\sqrt{A} = \sum_{k=0}^{\infty} \binom{p}{k} (A - I)^k$$

$$\Rightarrow \sqrt{\cdot} \text{ is analytic}$$

$$\Rightarrow \sqrt{ABA} = A\sqrt{BA}.$$

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Basic terms

**We shall need**

Motivation

Theory

Application

Conclusion





## Block-rotations

- Euclidean case:

$$\begin{bmatrix} \sqrt{I - XX^*} & X \\ -X^* & \sqrt{I - X^*X} \end{bmatrix},$$

- Hyperbolic case (Veselić):

$$\begin{bmatrix} \sqrt{I - XJ_2X^*J_1} & X \\ -J_2X^*J_1 & \sqrt{I - J_2X^*J_1X} \end{bmatrix}, \quad J = \text{diag}(J_1, J_2).$$

Obviously, both are ( $J$ -)unitary.

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Basic terms

**We shall need**

Motivation

Theory

Application

Conclusion

# SVD

- Euclidean case (traditional SVD):

$A = U\Sigma V^*$ ,  $U^*U = I$ ,  $V^*V = I$ ,  $\Sigma = \text{diag}(\sigma_i)$ ,  $\sigma_i \geq 0$ ,  
Exists for any  $A$ .

- Hyperbolic case (2HSVD – two-sided hyperbolic SVD):

$A = U\Sigma V^*$ ,  $U^*JU = J$ ,  $V^*JV = J$ ,  $\Sigma = \text{diag}(\sigma_i)$ ,  $\sigma_i J_{ii} \geq 0$ ,  
Exists if and only if  $A^{[*]}A$  is  $\mathbb{R}_0^+$ -diagonalizable and  $A$  is  
nondegenerate ( $\text{rank } A = \text{rank } A^*JA$ ).



*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Basic terms

**We shall need**

Motivation

Theory

Application

Conclusion



## Polar decomposition

- Euclidean case (traditional polar decomposition):

$$A = UP, \quad U^*U = I,$$

$P$  is positive semidefinite Hermitian.

Exists for any square  $A$ .

- Hyperbolic case (semidefinite  $J$ -polar decomposition by Bolshakov et al):

$$A = UP, \quad U^*JU = J, \quad P \text{ is } J\text{-nonnegative,}$$

i.e.  $JP$  is positive semidefinite.

Exists under some complex conditions.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Basic terms

**We shall need**

Motivation

Theory

Application

Conclusion

2HSVD and semidefinite  $J$ -polar decomposition

$J$ -polar decomposition + nondegeneracy  $\Leftrightarrow$  2HSVD.



## Polar decomposition

- Euclidean case (traditional polar decomposition):

$$A = UP, \quad U^*U = I,$$

$P$  is positive semidefinite Hermitian.

Exists for any square  $A$ .

- Hyperbolic case (semidefinite  $J$ -polar decomposition by Bolshakov et al):

$$A = UP, \quad U^*JU = J, \quad P \text{ is } J\text{-nonnegative,}$$

i.e.  $JP$  is positive semidefinite.

Exists under some complex conditions.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Basic terms

**We shall need**

Motivation

Theory

Application

Conclusion

2HSVD and semidefinite  $J$ -polar decomposition

$J$ -polar decomposition + nondegeneracy  $\Leftrightarrow$  2HSVD.



# QR decomposition

- Euclidean case:

$$A = QR, \quad Q^*Q = I, \quad R \text{ upper triangular,}$$

- Hyperbolic case (Singer):

$$A = P_1 Q R P_2^*, \quad Q^* J' Q = J', \quad J' = P_1^* J P_1,$$

$R$  is upper block-triangular with diagonal blocks of order 1 or 2.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Basic terms

**We shall need**

Motivation

Theory

Application

Conclusion

## Block operations

We shall decompose a  $J$ -unitary matrix  $U$  into a product of a block  $J$ -rotation and a block-diagonal  $J$ -unitary matrix:

$$U = R\Delta.$$

Generalization of a corresponding Euclidean result.

Example: Hyperbolic QR

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} + \text{one block rotation} \Rightarrow A'_{21} = 0$$



*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Basic terms

We shall need

**Motivation**

Theory

Application

Conclusion



## Block operations

We shall decompose a  $J$ -unitary matrix  $U$  into a product of a block  $J$ -rotation and a block-diagonal  $J$ -unitary matrix:

$$U = R\Delta.$$

Generalization of a corresponding Euclidean result.

### Example: Hyperbolic QR

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} + \text{one block rotation} \Rightarrow A'_{21} = 0$$

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Basic terms

We shall need

**Motivation**

Theory

Application

Conclusion

# Theory

- 1 Introduction
- 2 Theory
  - Theorems
  - Outlines of the proofs
- 3 Application
- 4 Conclusion



*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

**Theory**

Theorems  
Proofs

Application

Conclusion





## Euclidean case (Zakrajšek and Vidav)

For unitary

$$U = \begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix}$$

exist unitary

$$R = \begin{bmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{bmatrix} \quad \text{and} \quad \Delta = \begin{bmatrix} \Delta_{11} & \\ & \Delta_{22} \end{bmatrix}$$

such that  $U = R\Delta$  and

$$R_{11} = \sqrt{I + R_{12}R_{21}}, \quad R_{21} = -R_{12}^*, \quad R_{22} = \sqrt{I + R_{21}R_{12}}.$$

Note: If  $U$ ,  $R$  and  $\Delta$  are of order 2,  $R$  is a (trigonometric) rotation.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

**Theorems**  
Proofs

Application

Conclusion



## Euclidean case (Zakrajšek and Vidav)

For unitary

$$U = \begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix}$$

exist unitary

$$R = \begin{bmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{bmatrix} \quad \text{and} \quad \Delta = \begin{bmatrix} \Delta_{11} & \\ & \Delta_{22} \end{bmatrix}$$

such that  $U = R\Delta$  and

$$R_{11} = \sqrt{I + R_{12}R_{21}}, \quad R_{21} = -R_{12}^*, \quad R_{22} = \sqrt{I + R_{21}R_{12}}.$$

**Note:** If  $U$ ,  $R$  and  $\Delta$  are of order 2,  $R$  is a (trigonometric) rotation.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

**Theorems**  
Proofs

Application

Conclusion



## Hyperbolic case

For  $J$ -unitary

$$U = \begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix}, \quad J = \text{diag}(J_1, J_2),$$

if 2HSVDs of  $U_{11}$  and  $U_{22}$  exist, then there also exist  $J$ -unitary

$$R = \begin{bmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{bmatrix} \quad \text{and} \quad \Delta = \begin{bmatrix} \Delta_{11} & \\ & \Delta_{22} \end{bmatrix}$$

such that  $U = R\Delta$  and

$$R_{11} = \sqrt{I + R_{12}R_{21}}, \quad R_{21} = -J_2 R_{12}^* J_1, \quad R_{22} = \sqrt{I + R_{21}R_{12}}.$$

Note: If  $U$ ,  $R$  and  $\Delta$  are of order 2,  $R$  is a trigonometric (if  $J_1 = J_2$ ) or hyperbolic rotation (if  $J_1 = -J_2$ ).

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

**Theorems**  
Proofs

Application

Conclusion



## Hyperbolic case

For  $J$ -unitary

$$U = \begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix}, \quad J = \text{diag}(J_1, J_2),$$

if 2HSVDs of  $U_{11}$  and  $U_{22}$  exist, then there also exist  $J$ -unitary

$$R = \begin{bmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{bmatrix} \quad \text{and} \quad \Delta = \begin{bmatrix} \Delta_{11} & \\ & \Delta_{22} \end{bmatrix}$$

such that  $U = R\Delta$  and

$$R_{11} = \sqrt{I + R_{12}R_{21}}, \quad R_{21} = -J_2 R_{12}^* J_1, \quad R_{22} = \sqrt{I + R_{21}R_{12}}.$$

**Note:** If  $U$ ,  $R$  and  $\Delta$  are of order 2,  $R$  is a trigonometric (if  $J_1 = J_2$ ) or hyperbolic rotation (if  $J_1 = -J_2$ ).

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

**Theorems**  
Proofs

Application

Conclusion



## Euclidean case

- 1 Polar decomposition:  $U_{11} = R_{11}\Delta_1$ ,  $U_{22} = R_{22}\Delta_2$ .
- 2  $U$  unitary  $\Rightarrow R_{11} = \sqrt{I - R_{12}R_{12}^*}$ ,  $R_{22} = \sqrt{I - R_{21}R_{21}^*}$ .  
Also:  $R_{11}(R_{12} + R_{21}^*) = 0$  and  $(R_{12} + R_{21}^*)R_{22} = 0$ .
- 3 If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.
- 4 Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ positive real diagonal,}$$

solved through some ugly formulas

- 5 SVD:  $R_{11} = V_1\Sigma_1W_1^*$  and  $R_{22} = V_2\Sigma_2W_2^*$   
Apply previous step  $\Rightarrow$  extra unitary matrix on the left:

$$U = R'\Delta' = VR''(W^*\Delta').$$

Using  $\sqrt{ABA} = A\sqrt{BA}$  and some not-too-ugly formulas,  
 $V$  goes to the right hand side  $\Rightarrow$  Q.E.D.

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Theory

Theorems  
**Proofs**

Application

Conclusion



## Euclidean case

- 1 Polar decomposition:  $U_{11} = R_{11}\Delta_1$ ,  $U_{22} = R_{22}\Delta_2$ .
- 2  $U$  unitary  $\Rightarrow R_{11} = \sqrt{I - R_{12}R_{12}^*}$ ,  $R_{22} = \sqrt{I - R_{12}^*R_{12}}$ .  
Also:  $R_{11}(R_{12} + R_{21}^*) = 0$  and  $(R_{12} + R_{21}^*)R_{22}^* = 0$ .
- 3 If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.
- 4 Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ positive real diagonal,}$$

solved through some ugly formulas.

- 5 SVD:  $R_{11} = V_1\Sigma_1W_1^*$  and  $R_{22} = V_2\Sigma_2W_2^*$   
Apply previous step  $\Rightarrow$  extra unitary matrix on the left:

$$U = R'\Delta' = VR''(W^*\Delta').$$

Using  $\sqrt{ABA} = A\sqrt{BA}$  and some not-too-ugly formulas,  
 $V$  goes to the right hand side  $\Rightarrow$  Q.E.D.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems  
**Proofs**

Application

Conclusion



## Euclidean case

- 1 Polar decomposition:  $U_{11} = R_{11}\Delta_1$ ,  $U_{22} = R_{22}\Delta_2$ .
- 2  $U$  unitary  $\Rightarrow R_{11} = \sqrt{I - R_{12}R_{12}^*}$ ,  $R_{22} = \sqrt{I - R_{12}^*R_{12}}$ .  
Also:  $R_{11}(R_{12} + R_{21}^*) = 0$  and  $(R_{12} + R_{21}^*)R_{22}^* = 0$ .
- 3 If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.

- 4 Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ positive real diagonal,}$$

solved through some ugly formulas.

- 5 SVD:  $R_{11} = V_1\Sigma_1W_1^*$  and  $R_{22} = V_2\Sigma_2W_2^*$   
Apply previous step  $\Rightarrow$  extra unitary matrix on the left:

$$U = R'\Delta' = VR''(W^*\Delta').$$

Using  $\sqrt{ABA} = A\sqrt{BA}$  and some not-too-ugly formulas,  
 $V$  goes to the right hand side  $\Rightarrow$  Q.E.D.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems  
**Proofs**

Application

Conclusion



## Euclidean case

- 1 Polar decomposition:  $U_{11} = R_{11}\Delta_1$ ,  $U_{22} = R_{22}\Delta_2$ .
- 2  $U$  unitary  $\Rightarrow R_{11} = \sqrt{I - R_{12}R_{12}^*}$ ,  $R_{22} = \sqrt{I - R_{12}^*R_{12}}$ .  
Also:  $R_{11}(R_{12} + R_{21}^*) = 0$  and  $(R_{12} + R_{21}^*)R_{22}^* = 0$ .
- 3 If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.
- 4 Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ positive real diagonal,}$$

solved through some ugly formulas.

- 5 SVD:  $R_{11} = V_1\Sigma_1W_1^*$  and  $R_{22} = V_2\Sigma_2W_2^*$   
Apply previous step  $\Rightarrow$  extra unitary matrix on the left:

$$U = R'\Delta' = VR''(W^*\Delta').$$

Using  $\sqrt{ABA} = A\sqrt{BA}$  and some not-too-ugly formulas,  
 $V$  goes to the right hand side  $\Rightarrow$  Q.E.D.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems  
Proofs

Application

Conclusion





## Euclidean case

- 1 Polar decomposition:  $U_{11} = R_{11}\Delta_1$ ,  $U_{22} = R_{22}\Delta_2$ .
- 2  $U$  unitary  $\Rightarrow R_{11} = \sqrt{I - R_{12}R_{12}^*}$ ,  $R_{22} = \sqrt{I - R_{12}^*R_{12}}$ .  
Also:  $R_{11}(R_{12} + R_{21}^*) = 0$  and  $(R_{12} + R_{21}^*)R_{22}^* = 0$ .
- 3 If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.
- 4 Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ positive real diagonal,}$$

solved through some ugly formulas.

- 5 SVD:  $R_{11} = V_1\Sigma_1W_1^*$  and  $R_{22} = V_2\Sigma_2W_2^*$   
Apply previous step  $\Rightarrow$  extra unitary matrix on the left:

$$U = R'\Delta' = \mathbf{V}R''(W^*\Delta').$$

Using  $\sqrt{ABA} = A\sqrt{BA}$  and some not-too-ugly formulas,  
 $V$  goes to the right hand side  $\Rightarrow$  Q.E.D.

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Theory

Theorems  
Proofs

Application

Conclusion



## Hyperbolic case (polar decomposition)

- ① Semidefinite  $J$ -polar decomposition:

$$U_{11} = R'_{11} \Delta'_1, \quad U_{22} = R'_{22} \Delta'_2.$$

- ②  $U$   $J$ -unitary  $\Rightarrow$

Easy:  $(R'_{11})^2 = I - R'_{12} J_2 (R'_{21})^* J_1.$

But:  $R'_{11} \neq \sqrt{I - R'_{12} J_2 (R'_{21})^* J_1}$

Instead:

$$R_{11} := R'_{11} (V_1 J_1 V_1^{[*]}) \text{ and } R_{22} := R'_{22} (V_2 J_2 V_2^{[*]})$$

$V_1$  and  $V_2$  — from 2HSVD of  $R'_{11}$  and  $R'_{22}$

Then:

$$R_{11} (R_{12} J_2 + J_1 R_{21}^*) = 0 \text{ and } (R_{12} J_2 + J_1 R_{21}^*) R_{22} = 0.$$

- ③ If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.

Note:  $V_1 J_1 V_1^{[*]} \neq J_1, I$  ( $V_1 J_1 V_1^* = J_1, V_1 V_1^{[*]} = I$ )

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion



## Hyperbolic case (polar decomposition)

- ① Semidefinite  $J$ -polar decomposition:

$$U_{11} = R'_{11} \Delta'_1, \quad U_{22} = R'_{22} \Delta'_2.$$

- ②  $U$   $J$ -unitary  $\Rightarrow$

Easy:  $(R'_{11})^2 = I - R'_{12} J_2 (R'_{21})^* J_1.$

But:  $R'_{11} \neq \sqrt{I - R'_{12} J_2 (R'_{21})^* J_1}$

Instead:

$$R_{11} := R'_{11} (V_1 J_1 V_1^{[*]}) \text{ and } R_{22} := R'_{22} (V_2 J_2 V_2^{[*]})$$

$V_1$  and  $V_2$  — from 2HSVD of  $R'_{12}$  and  $R'_{21}$ .

Then:

$$R_{11} (R_{12} J_2 + J_1 R_{21}^*) = 0 \text{ and } (R_{12} J_2 + J_1 R_{21}^*) R_{22}^* = 0.$$

- ③ If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.

Note:  $V_1 J_1 V_1^{[*]} \neq J_1, I \quad (V_1 J_1 V_1^* = J_1, V_1 V_1^{[*]} = I)$

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

- Outline
- Introduction
- Theory
- Theorems
- Proofs**
- Application
- Conclusion



## Hyperbolic case (polar decomposition)

- ① Semidefinite  $J$ -polar decomposition:

$$U_{11} = R'_{11} \Delta'_1, \quad U_{22} = R'_{22} \Delta'_2.$$

- ②  $U$   $J$ -unitary  $\Rightarrow$

Easy:  $(R'_{11})^2 = I - R'_{12} J_2 (R'_{21})^* J_1.$

But:  $R'_{11} \neq \sqrt{I - R'_{12} J_2 (R'_{21})^* J_1}.$

Instead:

$$R_{11} := R'_{11} (V_1 J_1 V_1^{[*]}) \text{ and } R_{22} := R'_{22} (V_2 J_2 V_2^{[*]})$$

$V_1$  and  $V_2$  — from 2HSVD of  $R'_{12}$  and  $R'_{21}$ .

Then:

$$R_{11} (R_{12} J_2 + J_1 R_{21}^*) = 0 \text{ and } (R_{12} J_2 + J_1 R_{21}^*) R_{22}^* = 0.$$

- ③ If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.

Note:  $V_1 J_1 V_1^{[*]} \neq J_1, I \quad (V_1 J_1 V_1^* = J_1, V_1 V_1^{[*]} = I)$

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion



## Hyperbolic case (polar decomposition)

- ① Semidefinite  $J$ -polar decomposition:

$$U_{11} = R'_{11} \Delta'_1, \quad U_{22} = R'_{22} \Delta'_2.$$

- ②  $U$   $J$ -unitary  $\Rightarrow$

Easy:  $(R'_{11})^2 = I - R'_{12} J_2 (R'_{21})^* J_1.$

But:  $R'_{11} \neq \sqrt{I - R'_{12} J_2 (R'_{21})^* J_1}.$

Instead:

$$R_{11} := R'_{11} (V_1 J_1 V_1^{[*]}) \text{ and } R_{22} := R'_{22} (V_2 J_2 V_2^{[*]})$$

$V_1$  and  $V_2$  — from 2HSVD of  $R'_{11}$  and  $R'_{22}$ .

Then:

$$R_{11} (R_{12} J_2 + J_1 R_{21}^*) = 0 \text{ and } (R_{12} J_2 + J_1 R_{21}^*) R_{22}^* = 0.$$

- ③ If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.

**Note:**  $V_1 J_1 V_1^{[*]} \neq J_1, \mid (V_1 J_1 V_1^* = J_1, V_1 V_1^{[*]} = I)$

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion



## Hyperbolic case (polar decomposition)

- ① Semidefinite  $J$ -polar decomposition:

$$U_{11} = R'_{11} \Delta'_1, \quad U_{22} = R'_{22} \Delta'_2.$$

- ②  $U$   $J$ -unitary  $\Rightarrow$

Easy:  $(R'_{11})^2 = I - R'_{12} J_2 (R'_{21})^* J_1.$

But:  $R'_{11} \neq \sqrt{I - R'_{12} J_2 (R'_{21})^* J_1}.$

Instead:

$$R_{11} := R'_{11} (V_1 J_1 V_1^{[*]}) \text{ and } R_{22} := R'_{22} (V_2 J_2 V_2^{[*]})$$

$V_1$  and  $V_2$  — from 2HSVD of  $R'_{11}$  and  $R'_{22}$ .

Then:

$$R_{11} (R_{12} J_2 + J_1 R_{21}^*) = 0 \text{ and } (R_{12} J_2 + J_1 R_{21}^*) R_{22}^* = 0.$$

- ③ If  $R_{11}$  or  $R_{22}$  nonsingular  $\Rightarrow$  Q.E.D.

**Note:**  $V_1 J_1 V_1^{[*]} \neq J_1, \mid (V_1 J_1 V_1^* = J_1, V_1 V_1^{[*]} = I)$

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion



## Hyperbolic case (singular $U_{11}$ and $U_{22}$ )

- ④ Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ nonsingular real diagonal,}$$

solved through some ugly formulas.

Problem: 2HSVD does not group diagonal matrix (reminder: permutations are not always  $J$ -unitary).

- ④ Additional special case:

$$R_{11} = \text{diag}(\Sigma_1, \Sigma_2, \dots, \Sigma_k),$$

$\Sigma_i$  either zero or non-zero diagonal.

Solved using previous special case.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion



## Hyperbolic case (singular $U_{11}$ and $U_{22}$ )

- ④ Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ nonsingular real diagonal,}$$

solved through some ugly formulas.

**Problem:** 2HSVD does **not** group diagonal matrix (reminder: permutations are **not** always  $J$ -unitary).

- ④ Additional special case:

$$R_{11} = \text{diag}(\Sigma_1, \Sigma_2, \dots, \Sigma_k),$$

$\Sigma_i$  either zero or non-zero diagonal.

Solved using previous special case.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion





## Hyperbolic case (singular $U_{11}$ and $U_{22}$ )

- ④ Special case:

$$R_{11} = \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix}, \quad \Sigma \text{ nonsingular real diagonal,}$$

solved through some ugly formulas.

**Problem:** 2HSVD does **not** group diagonal matrix (reminder: permutations are **not** always  $J$ -unitary).

- ④ Additional special case:

$$R_{11} = \text{diag}(\Sigma_1, \Sigma_2, \dots, \Sigma_k),$$

$\Sigma_i$  either zero or non-zero diagonal.

Solved using previous special case.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion



## Hyperbolic case (singular $U_{11}$ and $U_{22}$ )

5 Like Euclidean case:

2HSVD:  $R_{11} = V_1 \Sigma_1 W_1^{[*]}$  and  $R_{22} = V_2 \Sigma_2 W_2^{[*]}$

Apply previous step  $\Rightarrow$  extra unitary matrix on the left:

$$U = R' \Delta' = \mathbf{V} R'' (W^* \Delta')$$

Using  $\sqrt{ABA} = A\sqrt{BA}$  and some not-too-ugly formulas,  
 $V$  goes to the right hand side  $\Rightarrow$  Q.E.D.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Theorems

**Proofs**

Application

Conclusion

# Application

- 1 Introduction
- 2 Theory
- 3 Application**
  - Example
- 4 Conclusion



*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Theory

**Application**

Example

Conclusion



## Block-operations

- Limited use, due to strict conditions,
- Special cases when 2HSVD always exists:

$$J = \text{diag}(\pm J_1, \pm J_2),$$

where  $J_k$  ( $k = 1, 2$ ) defines Euclidean ( $J_k = I$ ) product.

- Idea:
  - 1 use  $R_{12}$  and/or  $R_{21}$  for block-elimination of hyperbolic parts,
  - 2 use  $\Delta_1$  and  $\Delta_2$  on Euclidean spaces.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

Example

Conclusion



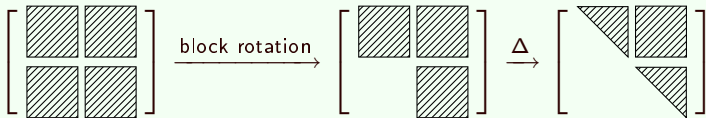
## Hyperbolic QR

- $P_1^* A P_2 = QR$ ,  $Q^* J' Q = J'$ ,  $J' = P_1^* J P_1$ ,
- $R$  is upper block-triangular with diagonal blocks of order 1 or 2.

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

### The idea



Assume: there exists HQR such that

$$J' = \text{diag}(I_k, -I_{n-k}) \text{ or, equivalently, } J' = \text{diag}(-I_k, I_{n-k})$$

Note:  $\Delta$  — from traditional (Euclidean) QR

Outline

Introduction

Theory

Application

**Example**

Conclusion



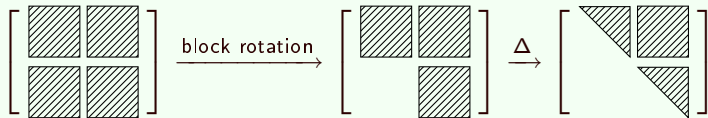
## Hyperbolic QR

- $P_1^* A P_2 = QR$ ,  $Q^* J' Q = J'$ ,  $J' = P_1^* J P_1$ ,
- $R$  is upper block-triangular with diagonal blocks of order 1 or 2.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

### The idea



Assume: there exists HQR such that

$$J' = \text{diag}(I_k, -I_{n-k}) \text{ or, equivalently, } J' = \text{diag}(-I_k, I_{n-k}).$$

**Note:**  $\Delta$  — from traditional (Euclidean) QR

Outline

Introduction

Theory

Application

**Example**

Conclusion



## Obtaining block rotation

We have:

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}, \quad J' = \begin{bmatrix} I_k & \\ & -I_{n-k} \end{bmatrix}.$$

Block-rotation:

$$\begin{aligned} B(X) &:= \begin{bmatrix} \sqrt{I_k - XJ'_2X^*J'_1} & X \\ -J'_2X^*J'_1 & \sqrt{I_{n-k} - J'_2X^*J'_1X} \end{bmatrix} \\ &= \begin{bmatrix} \sqrt{I_k - X(-I_{n-k})X^*I_k} & X \\ -(-I_{n-k})X^*I_k & \sqrt{I_{n-k} - (-I_{n-k})X^*I_kX} \end{bmatrix} \\ &= \begin{bmatrix} \sqrt{I_k + XX^*} & X \\ X^* & \sqrt{I_k + X^*X} \end{bmatrix} \end{aligned}$$

**Note:**  $J'_1$ - and  $J'_2$ -2HSVD  $\Leftrightarrow$  Traditional SVD!

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

**Example**

Conclusion



## Obtaining block rotation

We need  $X$  such that

$$B(X)A = \begin{bmatrix} R'_{11} & R'_{12} \\ 0 & R'_{22} \end{bmatrix}.$$

In other words:

$$\begin{bmatrix} \sqrt{I_k + XX^*} & X \\ X^* & \sqrt{I_k + X^*X} \end{bmatrix} \cdot \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} = \begin{bmatrix} R'_{11} & R'_{12} \\ 0 & R'_{22} \end{bmatrix},$$

i.e.

$$X^*A_{11} + \sqrt{I_k + X^*X}A_{21} = 0.$$

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

**Example**

Conclusion





## Finding $X$

If  $A_{11}$  non-singular, let  $A_{21}A_{11}^{-1} = V\Sigma W^*$  be (traditional) SVD of  $A_{21}A_{11}^{-1}$ .

Then  $X = -W\Sigma \left( \sqrt{I_k - \Sigma^2} \right)^{-1} V^*$ , so

$$\begin{aligned} X^*A_{11} + \sqrt{I_k} + X^*XA_{21} &= (X^* + \sqrt{I_k + X^*XA_{21}A_{11}^{-1}})A_{11} \\ &= (X^* + \sqrt{I_k + V\Sigma^2(I_k - \Sigma^2)^{-1}V^*V\Sigma W^*})A_{11} \\ &= (X^* + V\Sigma \left( \sqrt{I_k - \Sigma^2} \right)^{-1} W^*)A_{11} \\ &= (X^* - X^*)A_{11} = 0. \end{aligned}$$

**Note:** we need  $\left( \sqrt{I_k - \Sigma^2} \right)^{-1}$

*One decomp. of  
hyperbolic  
unitary matrices*

V.Šego

Outline

Introduction

Theory

Application

**Example**

Conclusion



## Finding $X$

Column “norms” (diagonal elements – must be nonnegative):

$$\begin{aligned}
 \begin{bmatrix} A_{11}^* & A_{21}^* \end{bmatrix} \begin{bmatrix} J_1' \\ J_2' \end{bmatrix} \begin{bmatrix} A_{11} \\ A_{21} \end{bmatrix} &= A_{11}^* A_{11} - A_{21}^* A_{21} \\
 &= A_{11}^* (I_k - (A_{21} A_{11}^{-1})^* (A_{21} A_{11}^{-1})) A_{11} \\
 &= A_{11}^* W (I_k - \Sigma^2) W^* A_{11}
 \end{aligned}$$

Left side positive definite  $\Leftrightarrow I_k - \Sigma^2 > 0$   
 $\Rightarrow \exists \sqrt{I_k - \Sigma^2}$

→ Column permutations ( $P_2$  in hyperbolic QR)

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

**Example**

Conclusion



## The algorithm

① Find  $P_1$  such that  $J' =: P_1^* J P_1 = \text{diag}(I_k, I_{n-k})$ ,

② Find  $P_2$  such that diagonal elements in

$$N := P_2^* A^* J' A P_2$$

have signs corresponding to  $J'$ ,

③ Check if the leading principal  $k \times k$  submatrix  $N[1 : k, 1 : k]$  is positive definite,

④ Find  $X$  (or, better,  $B(X)$ ),

⑤ Apply block-rotation to obtain  $A'$  from  $A$  (such that the bottom left block is 0),

⑥ Apply traditional QR on diagonal blocks of  $A'$ .

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

**Example**

Conclusion

# Conclusion

- 1 Introduction
- 2 Theory
- 3 Application
- 4 Conclusion**



*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

**Conclusion**



## To do

- 1 Expand the theory (add left and/or right permutations),
- 2 Find good algorithm for obtaining  $B(X)$ ,
- 3 Find general block-HQR (for any  $J$ ),
- 4 Apply the principle to other hyperbolic decompositions.

*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

Conclusion

## To do

- 1 Expand the theory (add left and/or right permutations),
- 2 Find good algorithm for obtaining  $B(X)$ ,
- 3 Find general block-HQR (for any  $J$ ),
- 4 Apply the principle to other hyperbolic decompositions.



*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

Conclusion

## To do

- 1 Expand the theory (add left and/or right permutations),
- 2 Find good algorithm for obtaining  $B(X)$ ,
- 3 Find general block-HQR (for any  $J$ ),
- 4 Apply the principle to other hyperbolic decompositions.



*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

Conclusion

## To do

- 1 Expand the theory (add left and/or right permutations),
- 2 Find good algorithm for obtaining  $B(X)$ ,
- 3 Find general block-HQR (for any  $J$ ),
- 4 Apply the principle to other hyperbolic decompositions.



*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

Conclusion





*One decomp. of  
hyperbolic  
unitary matrices*

V. Šego

Outline

Introduction

Theory

Application

Conclusion

## Questions?

Vedran Šego, vsego@math.hr

Faculty of Science, Department of Mathematics, University of Zagreb